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AIR CLIMATE & ENERGY RESEARCH PROGRAM

BUILDING A SCIENTIFIC FOUNDATION FOR SOUND ENVIRONMENTAL DECISIONS

SPod Progress EPA SPod Team - July, 2016



U.S. Environmental Protection Agency Office of Research and Development NRMRL Fugitive and Area Source Group Source and Fence Line Measurements Methods and Technology Development

SPod Update Description

The purpose of these slides are to provide an update on SPod research progress. These slides will be posted on the SPod Share drive and will be updated periodically.

This information should be used in conjunction with "SPod Fenceline Sensor Draft Design Package" and associated publications to understand the device and its limitations.

The SPod is a low cost, solar-powered system that combines wind field and air pollutant concentration measurements to detect emission plumes and help locate the source of emissions. The current design works only in "near-fenceline" applications where localized source emission plumes may be present.

This presentation addresses the following topics:

- General concepts of next generation emissions measurements
- What is an SPod and what it will do
- Mobile and fixed-place applications
- A review of current SPod design
- An example application of SPods used in conjunction with passive sampling
- Baseline performance of the current design
- Upcoming field studies



EPA SPod Research Team

- Bill Mitchell Electronics and system software design
- Bill Squier Mechanical design and application research
- Ryan Daly Mechanical and assembly design
- Dave Nash Fenceline methods and software
- Halley Brantley Analysis software
- Ingrid George Speciated analysis
- Jason Dewees Fenceline methods
- John Masters Communications
- Cary Secrest Applications research (future)
- EPA Regions R3,R4, R5, R6, R8 applications research (future)
- Eben Thoma Application coordination, method research



Next Generation Air Measurement (NGAM)

<u>Takeaways:</u>

SPods are part of the NGAM spectrum and can contribute in several ways

SPods have strengths and weaknesses

SPods work best with other approaches such as passive samplers and canisters





What is an SPod?





What is an SPod?

A lower cost mobile or fixed-place sensor system that helps detect, locate, and characterize air pollutant sources.

Where are SPods used?

Near potential emission sources, but not in hazardous zones.

Is there only one type of SPod?

No, EPA has a research SPod design (described here) but we are sharing information with system developers and we know several "SPod-like" systems are in development.



What can the EPA SPod currently measure?

Gas phase compounds detectable with a 10.6 eV PID.

Does the SPod produce a speciated measure of benzene or other compounds?

No, but it can be used with passive samplers and canisters.

Can the SPod produce a stable, calibrated measure? Not easily due to sensor and source effects.

Can the SPod be used far away from sources (ambient)? Not the EPA SPod (detection and stability-limited)





Example of OTM 33 GMAP mobile and fixed-place SPod leak detection application at a facility

VOC/HAP

Leak

Google ea

A mobile SPod

A fixed-place SPod

©2013 Geogle

Wind

Wind inverse source algorithm Example of SPod in oil and gas application 10

25 feet

This is an infrared camera video illustrating the emission plume from an oil and gas process malfunction

SPods look at highly variable plume signals Pollutant concentration - wind direction - time resolution



SPods are low cost, uncontrolled sensors.

You need to decouple source signal from baseline drift

This is why SPods are only used near sources



Older versions of SPod had a lot of baseline drift

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SPod Signals After Baseline Removal







A look at the SPod Sensor design

EPA ORD Open Source Draft Design April 7 , 2016

For access to the share drive, please email John Masters and Eben Thoma







The current SPod sensor is a 10.6 eV photoionization detector (PID)What can it see?

Let's take a look at a PID Table

http://goodforgas.com/wpcontent/uploads/2013/12/TN2004_PID_gas_table_01_16 _09.pdf





Philly Study (Version 1 SPods)

Project Elements

- (1) Passive Samplers
- (2) Fence line Sensors
- (3) Advanced Modeling
- (4) Optical Remote Sensing (City-AMS)







Deployment Area in South Philly

20

10

7.2 km

8

6

140

39°54'55.42" N 75°11'49.53" W elev 0 ft

Eye alt 29524 ft

S2010 Google

Passive

Samplers

17

Zoomed-in View of Philly study

Passive

Samplers

SPod

Combination of passive samplers and real-time sensors

©2010 GOOS

2367

Eye alt

UV DOAS

SPods

Sentinel Base Station



39°54'51.78" N 75°11'18.86" W elev 0 ft



Each point is a sampling location from slides 18, 19 with all passive sampler benzene data (June 2013-March 2015)



Each data point is a two-week passive sampler benzene measurement for the "fenceline group" consisting of locations 7-11. Period 1 is June2013, Period 42 is March 2015.

SPod and UV DOAS data from the elevated two-week period



On 11/15/14, both SPods show strong signal from the refinery to the west with the inverse algorithms pointing toward the source





Los Alamos National Lab Quick Urban & Industrial Complex (QUIC) Model

Modeled Source Locations

We can perform more sophisticated modeling to help located source signals. The QUIC model takes into account flow obstructions

> Spatial Gradient

Sensors and Models

Vegetation Barrier

Sensor Locations



QUIC model Run 7/05/14 6 hours – illustrative example This is a simulated source at an assumed location (not a real emission plume)

Example of SPod and QUIC model data from the Philly site. This is a QUIC plume evolution and flow movie based on SPod data

Concentration at Z = 1.5 (meters) ,Time = 300 (sec)



Draft 062015

and

Status:

We are going back to Philly with Version 2 SPods

A three-node network with one base station for communication











20 ppb Benzene Bump Test





New Philly Test, 3 nodes and base station, deployment target July 2016





New Philly System, 3 nodes one base station deployment target, July 2016

These are version 2 SPods with lower baseline drift







SPods Progress June, 2016

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