- Constraining U.S. ammonia emissions using TES
- ² remote sensing observations and the GEOS-Chem
- adjoint model

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4 Abstract.

- Ammonia (NH₃) is an important contributor to air pollution, and it also
- has significant impacts on climate change and environmental health. How-
- ever, there are many uncertainties in ammonia emissions inventories, from
- 8 the total amount of emissions to the seasonal and diurnal variability, which
- 9 hinder the use of air quality models to address these issues. In this paper,

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we constrain ammonia emissions in the U.S. by assimilating observations from the TES remote sensing instrument with the GEOS-Chem model and its adjoint at 2°×2.5° horizontal resolution. This inversion framework is first val-12 idated using simulated observations. We then proceed to assimilate TES observations for April, July and October of 2006 through 2009. The inverse modeling results are evaluated by comparing the observationally constrained model 15 simulations to independent surface measurements of NH_3 , NH_x ($NH_4^+ + NH_3$) wet deposition, and SO_4^{2-} and NO_3^- aerosol. Modeled NH_3 concentrations 17 have a decreased bias in April and October compared to surface observations after assimilation and an increased correlation in each month. Modeled NH_x 19 wet deposition after assimilation has a decreased normalized mean bias (NMB) in April and an increased NMB in July and October compared to the wet NH_x observations, although the correlation and linear regression coefficients 22 are closer to unity in each month. Modeled SO_4^{2-} and NO_3^- aerosols concen-23 trations do not change significantly and persistent NO₃ overestimation is noted, consistent with previous studies. Overall, assimilation of NH₃ remote sensing data to constrain NH₃ emissions improves the model simulation in several aspects, yet additional work on assessing wet deposition at a higher horizontal resolution, nitric acid formation, and bi-directional fluxes may be necessary to enhance model performance across the full range of gas and aerosol evaluations.

1. Introduction

Emissions of ammonia (NH₃) from anthropogenic sources pose several environmental 31 concerns. Ammonia affects air quality and climate through its role in the mass, composition and physical properties of tropospheric aerosol. Ammonium nitrate and ammonium 33 sulfate make up a substantial fraction of atmospheric fine particulate matter $(PM_{2.5})$, exposure to which has been statistically associated with inhibited lung development, cardiovascular diseases and premature mortality [Pope et al., 2002; Schwartz et al., 2002; Reiss et al., 2007. These fine particulates $(PM_{2.5})$ also contribute to haze that impacts visibility. Further, when deposited in excess, reactive nitrogen, including ammonia, can cause detrimental nutrient imbalances to sensitive ecosystems [Rodhe et al., 2002; Rabalais, 2002]. Despite the recognized importance of NH₃ emissions in the U.S. [Aneja et al., 2008], knowledge of their magnitude is severely limited; NH_3 emissions are primarily from agricultural sources whose strengths are difficult to characterize. Uncertainty in NH₃ undermines the efforts to understand historical and present levels of $PM_{2.5}$ [Yu et al., 2005; Nowak et al., 2006; Zhang et al., 2008; Wu et al., 2008; Stephen and Aneja, 2008; Beusen et al., 2008; Simon et al., 2008; Henze et al., 2009] and hinders estimates of the response of PM_{2.5} to control measures because of the key role that NH₃ plays in governing the balance of inorganic fine particulate species [Dennis et al., 2008]. Model estimates of inorganic PM_{2.5} have been compared to surface measurements [Park et al., 2004, 2006; Liao et al., 2007; Henze et al., 2009; Pye et al., 2009] and measurements from aircraft campaigns [Heald et al., 2005, 2006]; NH₃ emissions are frequently indicated to be a likely cause of discrepancies. On a larger scale, NH₃ emissions rates are a critical source of uncertainty in global budgets of the atmospheric transport and deposition of reactive nitrogen [Sutton et al., 2007; Galloway et al., 2008; Schlesinger, 2009].

These are several reasons for the persistence of uncertainties in NH₃ inventories. Characterizing NH₃ sources from the bottom up requires spatially and temporally resolved data such as detailed farming practices and intensity. These data are rarely available nationally as direct measurements of NH₃ emissions at such scales are prohibitive owing to cost. Therefore, people have turned to top-down approaches to provide additional constraints on NH₃ emissions estimates. While direct observations of gas-phase NH₃ do exist in select locations, observations of other chemically related species are much more prevalent. Further, NH₃ can rapidly partition to form aerosol ammonium (NH₄⁺) which can limit the utility of gas-phase observations alone.

Consequently, owing to the paucity of direct observations of NH₃ and the difficulty of constraining the NH_x (= NH₃ + NH₄⁺) system, measurements of species that are regulated by the amount of available NH₃ have been looked to for constraints on estimates of NH₃ emissions. The current National Emissions Inventory (NEI) for NH₃ is coarsely constrained by top-down estimates from the inverse modeling studies of *Gilliland et al.* [2003, 2006]. Measurements of wet deposited NH_x were used as constraints, because wet deposited NH_x estimates depend less than NH₃ on model sensitivity to aerosol partitioning. A drawback to this approach is the sensitivity to estimated precipitation and scavenging, aspects which are difficult to model accurately and hinder the inversion during some seasons. Taking an alternative approach, *Henze et al.* [2009] used measurements of SO₄²⁻ and NO₃⁻ from the IMPROVE network to constrain the amount of NH₃ partitioned

into the aerosol phase as NH₄⁺ (which is strongly coupled to SO₄²⁻ and NO₃⁻). In this way, aerosol-phase observations were used to constrain NH₃ concentrations and, hence, NH₃ emissions. This approach, however, is susceptible to model bias in HNO₃, which may be significant [*Zhang et al.*, 2012].

Despite these recent efforts, comparisons between inverse modeling results to the recent bottom-up NH₃ inventory of *Pinder et al.* [2006] show that considerable disagreements remain in the spatial and seasonal distribution of NH₃ emissions throughout the U.S. [*Henze et al.*, 2009]; at odds are estimates of the relative magnitude of spring vs summer emissions. A limiting factor in reconciling these differences is infrequent and sparse in situ observations, even for the aerosol-phase measurements, and a shortage of direct constraints on gas-phase NH₃. Without understanding the NH_x system as a whole, and without tools to link observations of these species over the continent to emissions, studies of NH₃ or NH₄ alone may suffer in terms of utility for constraining emissions inventories at a national scale [*Pinder et al.*, 2006].

The detection of boundary layer ammonia from space [Beer et al., 2008; Clarisse et al., 2009, 2010; Shephard et al., 2011] provides a new and unprecedented opportunity for reducing persistent uncertainties in our understanding of the distribution and impacts of atmospheric ammonia. Initial comparisons to global model NH₃ distributions indicate that NH₃ sources may be widely underestimated [Clarisse et al., 2009; Shephard et al., 2011].

Pinder et al. [2011] have recently verified the utility of such measurements for tracking observed spatial and temporal trends in surface level NH₃ concentrations. Therefore, we consider here how inverse modeling with assimilation of satellite observations of NH₃ can be used to further provide constraints on NH₃ sources. Section 2 describes the models

and inverse methodology used in this study. We then present details of the remote sensing
observations (Section 3), followed by inverse modeling tests using simulated observations
(Section 4), and real observations (Section 5). Finally, we evaluate the modeled results
by comparing them to independent data sets which are not used during the inversion
(Section 6) and present our conclusions (Section 7).

2. Methods

2.1. GEOS-Chem

GEOS-Chem is a chemical transport model driven with assimilated meteorology from 103 the Goddard Earth Observing System (GEOS) of the NASA Global Modeling and Assim-104 ilation Office [Bey et al., 2001]. The tropospheric oxidant chemistry simulation in GEOS-Chem includes a detailed ozone- NO_x -hydrocarbon chemical mechanism of 80 species and 106 over 300 reactions [Bey et al., 2001]. GEOS-Chem includes an online secondary inorganic aerosol simulation introduced and described in full by Park et al. [2004]. Global anthro-108 pogenic sources and natural sources of NH₃ are from the 1990 GEIA inventory [Bouwman 109 et al., 1997]. As described in Park et al. [2004], the yearly total U.S. NH₃ emissions are 110 scaled to match that of Gilliland et al. [2003], with seasonality based on temperature for 111 animals and soils [Aneja et al., 2000; Roelle and Aneja, 2002] and daylight [Adams et al., 112 1999 for crops and fertilizers. The biomass burning and biofuel use are from inventories 113 by Duncan et al. [2003] and Yevich and Logan [2003].

2.2. GEOS-Chem adjoint model

The adjoint model is an efficient method for calculating the gradient of a scalar model response function with respect to all of the model parameters simultaneously. The adjoint

of the GEOS-Chem model was developed specifically for inverse modeling of precursors of 117 inorganic PM_{2.5} with explicit inclusion of gas-phase chemistry, heterogeneous chemistry, and treatment of the thermodynamic couplings of the sulfate - ammonium - nitrate - water 119 aerosol system [Henze et al., 2007, 2009]. As the only adjoint model to explicitly represent this system, it is uniquely capable of assimilating speciated measurements of both gaseous 121 and particulate components using the 4D-Var method [Sandu et al., 2005]. The accuracy 122 of the adjoint model calculations is verified through extensive comparisons of adjoint to finite difference sensitivities. In order to maximize points of comparison between these 124 two approaches, we consider both ensembles of 1-D models (i.e., no horizontal transport) as well as spot tests of the full 3-D adjoint model (testing the full adjoint model for each 126 parameter is not feasible, as it would require separate forward model calculations for each 127 of the approximately 10⁵ parameters). Fig. 1 shows the results of a week-long test of the 128 sensitivity of surface level aerosol nitrate in each model column to NH₃ emissions in that 129 column, demonstrating the accuracy of the adjoint gradient calculation. 130

2.3. Inverse modeling

Data assimilation techniques provide a framework for combining observations and models to form an optimal estimation of the state of a system, which in this case is the chemical makeup of the troposphere. To start with, a range of parameters are typically constructed using control variables, σ , to adjust elements of the vector of model parameters, \mathbf{p} , via application as scaling factors, $p = p_a e^{\sigma}$, where $\mathbf{p_a}$ is the prior parameter estimate. The approach we consider iteratively employs the adjoint of an air quality model in a method referred to as 4D-Var, used here for inverse modeling of emissions. The advantage of this method is that numerous $(\mathcal{O}(10^5))$ model parameters can be optimized simultaneously while still retaining the constraints of the full forward model physics and chemistry. This
approach to inverse modeling seeks σ that minimizes the cost function, \mathcal{J} , given by

$$\mathcal{J} = \frac{1}{2} \sum_{\mathbf{c} \in \Omega} (H\mathbf{c} - (\mathbf{c}_{obs} - \mathbf{b}))^T \mathbf{S}_{obs}^{-1} (H\mathbf{c} - (\mathbf{c}_{obs} - \mathbf{b}))$$
$$+ \frac{1}{2} \gamma (\boldsymbol{\sigma} - \boldsymbol{\sigma}_a)^T \mathbf{S}_a^{-1} (\boldsymbol{\sigma} - \boldsymbol{\sigma}_a)$$
(1)

where H is the observation operator, γ is the regularization parameter, σ_a is the prior estimate of the control variables, S_a and S_{obs} are error covariance estimates of the control 142 variables and observations respectively, and Ω is the domain over which observations, 143 $\mathbf{c}_{\mathrm{obs}},$ and model predictions are available, and \mathbf{b} is a bias correction explained in section 5. Overall, the cost function is a specific model response, the minimum value of which balances the objectives of improving model performance while ensuring the model itself remains within a reasonable range (as dictated by \mathbf{S}_a^{-1}) of the initial model. Gradients 147 of the cost function with respect to the parameter scaling factors calculated with the adjoint model, $\nabla_{\sigma} \mathcal{J}$, are supplied to an optimization routine (the quasi-Newton L-BFGS-149 B optimization routine Byrd et al. [1995]; Zhu et al. [1994]), and the minimum of the cost function is sought iteratively. At each iteration, improved estimates of the model 151 parameters are updated and the forward model solution is recalculated.

3. Observations

3.1. Remotely sensed NH₃ observations from TES

The high spectral resolution and good signal-to-noise ratio of the TES instrument [Shephard et al., 2008] have enabled the first detection of tropospheric ammonia from space,
first demonstrated over Southern California and China [Beer et al., 2008]. TES is an
infrared Fourier transform spectrometer with spectral resolution of 0.06 cm⁻¹ aboard the

NASA Aura satellite, launched July 15, 2004 [Schoeberl et al., 2006]. TES global survey observations repeat with a 16-day cycle and have a nadir footprint of 5 km × 8 km; for example, that is about ~180 daytime retrievals a month over North America after cloud screening (optical depths < 1.0) and applying the TES retrieval quality control flags.

Comparison of model estimates to satellite observations is done via application of the following formula for the TES observational operator, H,

$$H\mathbf{c} = \mathbf{c}_a + \mathbf{A}(\mathbf{M}\mathbf{c} - \mathbf{c}_a) \tag{2}$$

where c is the model estimated NH₃ profile, M is a matrix that maps these values to the retrieval units and vertical levels, A is the averaging kernel, and c_a is the a priori 162 NH₃ profile used for the retrieval [Shephard et al., 2011]. By comparing TES NH₃ pro-163 files to mapped model estimates, $H\mathbf{c}$, rather than the native model NH₃ profile, \mathbf{c} , the 164 contribution of error in \mathbf{c}_a to the measurement error, \mathbf{S}_{obs} , is minimized [Rodgers, 2000]. 165 For the sake of 2D visualization, the Representative Volume Mixing Ratio (RVMR) 166 metric [Payne et al., 2009; Shephard et al., 2011] is used in this study to provide a means 167 of comparing TES profiles to model estimates in a manner that accounts for heterogeneity in the instrument's sensitivity to NH₃. 169

3.2. Surface measurements

In this study, model estimates are evaluated using surface observations of ammonia, sulfate, nitrate, ammonium and wet deposited NH_x from several monitoring networks throughout the U.S.. Surface NH_3 observations are from the National Atmospheric Deposition Program (NADP) Ammonia Monitoring Network (AMoN), which is comprised of triplicate passive ammonia monitoring samplers located at 21 sites across the U.S. with a two-week long sample accumulation. The locations of these 21 monitoring stations are shown in Fig. 2. Observations from each site are compared with modeled concentrations during the year November 2007 through June 2010.

Wet deposition observations are taken from the NADP National Trends Network (NTN)

(http://nadp.sws.uiuc.edu/NADP), which are predominantly located away from urban

areas and point sources of pollution. NTN has more than 200 sites with week-long sample

accumulation.

Model estimates of sulfate and nitrate aerosols are compared to observations from the Interagency Monitoring of Protected Visual Environments (IMPROVE) network for the year 2008 [Malm et al., 2004]. The IMPROVE network collects PM_{2.5} particles on Teflon, nylon, and quartz filters using a modular, cyclone-based sampler with critical orifice flow control. Sulfate and nitrate aerosols are collected on nylon filters, which are sampled over 24 h every third day.

4. Pseudo inversions

We first assess the capabilities and limitations of the GEOS-Chem inverse modeling
setup in idealized control conditions by designing inverse problems with known solutions.

Pseudo-observations are generated through application of the TES NH₃ retrieval algorithm

[Shephard et al., 2011] to a simulated atmosphere from GEOS-Chem. The emissions used
during this simulation are designated as the true emissions. Sampling times, locations and
error estimates reflect those of actual TES observations although retrieval bias (b) is not
included in these tests. For these tests, 87 pseudo TES observations are used from July 14
through 19, 2005, along roughly a dozen global survey transects crossing the midwestern
U.S..

To test the inverse model, NH₃ emissions parameters were initialized to values different 197 from the true emissions. In the first test, initial model emissions are half of the true value. Fig. 3(a) shows these values in black along with linear line slope m and r^2 . After 199 optimization, the recovered emissions are unbiased and have a visible variance around the true emissions of $\sim 30\%$, as shown in blue in Fig. 3(a). In a second test using the same 201 pseudo observations, the model emissions were initially biased high by a factor of 1.8 202 (Fig. 3(b)). The emissions recovered after optimization have a 20% high bias and again 203 a 30% variance about the true values. While the variance of the recovered emissions is 204 similar in both tests, the inversion starting with emissions that are initially too high is less successful. 206

To further investigate the reasons for this asymmetry and the variance of the optimized 207 emissions, additional tests are performed to separate the possible impacts of inversion 208 error, retrieval bias and measurement error. In each of the following tests, the true emis-209 sions are used to initialize the inversion. The first test uses the same pseudo observations 210 as previously generated. This test again results in a high bias. As the same model state is 211 used to generate the pseudo observations as was used to intialize the inversion, this bias can be attributed to a high bias in the retrieval itself. Retrieval bias, as explained further 213 in Shephard et al. [2011], is owing to the fact that the retrieval always selects a moderate or polluted profile as an initial guess in order to avoid the null space of the radiative trans-215 fer operator. As the optimal estimation algorithm iterates towards a solution, the process 216 may halt when values reach TES's detection threshold, resulting in a high bias. To test 217 this, the retrieval algorithm is modified to use only a moderate profile as an initial guess. 218 Pseudo observations generated using these profiles lead to slightly less high bias in the

inversion, at the cost of increased variance, see Fig. 4(b). As the magnitude of the final bias in tests whose results shown in (a) and (b) are similar to those in the pseudo inversions, it seems that the retrieval bias explains the bias exhibited in the pseudo inversions, 222 and thus the entire process of inverting for NH₃ emissions is not appreciably intrinsically biased. To isolate the impact of measurement noise, the model profiles from the true 224 model are applied with the same size error as the measurement error, and then assimi-225 lated. These profiles, unlike the previous tests, correspond directly to the true model and are not retrieved profiles from the retrieval process. The impact of this measurement noise 227 is only a slight adjustment in the emissions. Thus, the variance exhibited in the pseudo inversions is intrinsic to the inversion process itself, and would occur even if observations 229 were perfect. This happens because there are variations in emissions that lie in the null space of the forward model. In other words, having some emissions too high and some 231 emissions too low can result in indistinguishable (to TES) distributions of NH₃. Overall, 232 the pseudo observation tests lead us to conclude that (1) measurement noise alone will 233 not lead to unstable inversions (2) emissions that are underestimated can likely be recov-234 ered (3) emissions that are overestimated will be decreased, though this is countered by bias in the retrievals leading to overestimate of emissions in conditions where the model 236 emissions are intially too high and (4) that many more iterations and observations would be necessary to reduce the variance of the emissions estimates from the truth, which will 238 be at best $\sim 30\%$. While substantial, this is a significant improvement over initial errors 239 of $\sim 100\%$. Although between points (2) and (3) is likely owing to the larger magnitude of the bias for retrievals with larger values (see Supplementary Figure 1).

5. TES assimilation

We next proceed to constrain U.S. NH_3 sources using real observations. TES observations throughout 2006 - 2009 are compared to model estimates from a 2008 GEOS-Chem global $2^{\circ} \times 2.5^{\circ}$ simulation. Four years of observations are necessary to provide sufficient spatial data coverage. Inter-annual comparisons of monthly AMoN NH_3 data indicate no substantial trends in this time period.

Thousands of TES retrievals are available for the assimilation, but not all of the TES 247 retrievals are usable. The satellite can not always detect NH₃ for several reasons, such 248 as the presence of clouds, low NH_3 concentrations (low signal to the noise ratio), and poor thermal contrast between the earth and atmosphere. Thus quality and diagnostic 250 flags are defined to classify and filter the retrievals, keeping only those that have Degree Of Freedom For Signal (DOFS) greater than 0.1, or DOFS less than 0.1 but with high 252 (absolute value greater than 7 K) thermal contrast. We use the retrievals from daytime 253 only as the retrievals at night time do not appear to capture the diurnal variability of the 254 surface NH₃ concentrations and are currently being further studied. The TES retrievals 255 are corrected by subtracting mean biases. These biases are generated from the discrepancy between TES retrievals and true profiles [Shephard et al., 2011], and the mean biases are 257 calculated according to the type of the a priori profile (see Supplementary Figure 1).

A key aspect of inverse modeling is regularization through inclusion of the penalty, or background, term in the cost function. To define S_a , uncertainties of ammonia in the emissions inventories are assumed to be 100% of the maximum emissions of ammonia across the globe. Uncertainties of SO_2 and NO_x are 20% and 50% of the maximum emission of corresponding sources across the globe. We also assume the errors are uncorrelated. Using an L-curve selection criteria [Hansen, 1998] (see Supplementary Figure 2), we select the regularization parameter (γ) to be 124 for April, 100 for July, and 50 for October.

TES NH₃ observations are assimilated using the GEOS-Chem adjoint-based inversion.

The total initial and optimized ammonia emissions are shown in Fig. 5. The initial model estimates of NH₃ profiles are predominately lower than the observations. The optimized emissions generally increase over the entire U.S.. There are large increases in southern California in all three months. Other large increases are located in the central U.S., as well as Mexico and Cuba. We do not have much information about NH₃ in Mexico and Cuba due to lack of measurement records there, but large (e.g. 15 ppb) NH₃ RVMR values are observed in April whereas the corresponding GEOS-Chem model estimates using the initial emissions are very small (e.g. 1.37 ppb). As a result of the inversion, emissions are increased in such areas by up to a factor of 9.

The RVMR represents a TES sensitivity weighted boundary layer averaged value with 276 the influence of a priori reduced as much as possible [Shephard et al., 2011]. We calculate 277 RVMR only for retrievals that have high SNR and high thermal contrast. The RVMR is 278 also calculated for the model in those locations which have valid TES retrievals. Fig. 6 shows the comparison of NH₃ RVMR from TES and GEOS-Chem before and after the 280 assimilation. It has $500 \sim 700$ RVMR values in each month including values from 4 years. A linear fit of the model values to the observations is performed in each month, before and 282 after optimization. The slope of this line increases in each month which indicates that 283 most of the RVMR values from GEOS-Chem increase after the optimization. However, the modeled NH₃ RVMRs at low values change only slightly after the optimization in all three months. We note however that these differences in RVMR do not reflect observation bias

or uncertainty, which contribute to the cost function. In order to show the locations which
have significant changes in RVMR, we consider spatial plots of the difference between the
TES and GEOS-Chem RVMR before and after the assimilation for each month (Fig. 7).
Initially, the model RVMRs are generally less than the TES RVMRs, as indicated by the
blue points in the map. After the optimization, model RVMRs increase in many places.
Some of the model RVMRs are larger than the TES RVMRs, as indicated by the red points
in the map and the overall model bias relative to TES is reduced. The discrepancies of
TES RVMRs and model RVMRs change from negative to positive in Southern California
and Central U.S. in all three months, consistent with the spatial plots showing large
increases of ammonia emissions in these locations (Fig. 5).

We next assess the sensitivity of these results to the assumed a priori emissions errors, \mathbf{S}_a . Table 1 shows the effects of varying a priori errors on the total optimized emissions of different species. We assume $\mathbf{S}_a(\mathrm{NH}_3)$ to be 50% of the maximum a priori emission for all species. Generally, the results of the inversion are not very different in terms of total emission changes for each species from the base case inversion, see Table 1. However, absolute changes in total emissions of SO_2 and NO_x increase slightly as their uncertainties increase relative to those of NH_3 , while changes in NH_3 total emissions decrease as uncertainty of NH_3 decreases.

6. Evaluation

In the next section, we compare model estimates using the optimized emissions to independent data sets not used during the inversion.

6.1. AMoN

We first consider a comparison of the posterior model results to AMoN NH₃ observations (Fig. 8). Initially, the model broadly underestimates AMoN values. After optimization, 308 the $\mathrm{NH_{3}}$ concentrations increase in each month. The R^{2} increases by 22.4% in April, 28.9% in July and 27.2% in October. The slope increases by 353.3% in April, 96.1% in 310 July and 77.1% in October. However, while the root mean square error (RMSE) decreases 311 by 13% in April and 9.5% in October, it increases by 77.6% in July. The normalized mean 312 bias (NMB) after the optimization decreases from -0.678 to -0.069 in April, increases from 313 -0.045 and -0.138 to 0.659 and 0.166 in July and October, respectively. Overall, the model does a better job of capturing the range and variability of NH₃ at AMoN sites in April 315 and October, while in July, the model estimates are consistently biased high. 316

TES has a detection limit of about 1 ppb, and a positive bias of about 0.5 ppb [Shephard] 317 et al., 2011. We can see model values that are below 1 ppb do not change significantly 318 before and after the optimization in all three months (Fig. 8). The bias shown in Fig. 8 319 for July is much higher than 0.5 ppb. One possible reason may be the sampling bias of the 320 TES retrievals. This can be assessed by analyzing NH₃ simulations from high resolution $(12 \text{ km} \times 12 \text{ km})$ Community Multi-scale Air Quality (CMAQ) model simulations. Sur-322 face level NH₃ concentrations throughout the U.S. are compared to concentrations from locations corresponding to successful TES retrievals. The mean surface NH₃ concentra-324 tion of CMAQ at locations which have successful TES retrievals is about 30% larger than 325 the mean value of that for the whole U.S.. This comparison is facilitated by the fact that the TES footprint (5 km \times 8 km) and CMAQ grid cells are similar in size. As shown in Fig. 8, changes in large concentrations drive the optimization. A lack of TES observations

constraining low values may allow for initial model values that already overestimate low
NH₃ concentrations to become even higher in the optimized model, because high TES
values, many of which are larger than the initial model estimate will dominate the cost
function. In future work, resampling the TES retrievals may be one way to decrease the
sampling bias. Increasing the model resolution may also improve our ability to model
localized peak NH₃ concentrations measured by TES and to match observations from
AMoN.

6.2. NTN

As an additional check of the broad NH_x budget, we consider the NH_x wet deposition as recorded by NTN (NADP) sites. To make this comparison, we consider that simulated precipitation is a critical driver in the performance of the GEOS-Chem simulated wet deposition estimates, as biases in the model estimated precipitation can lead to biases in the GEOS-Chem model estimates. We therefore adjust the modeled wet deposition diagnostic to account for differences in the modeled and observed precipitation by linearly scaling the model estimated wet deposition by the ratio of the observed to estimated precipitation.

Figure 9 shows the comparison of modeled wet deposition with the NTN observations.

Generally, the inversion increases the wet deposition during all three months. Also correlation (R^2) improves in each month. The square of correlation coefficient (R^2) increases by 30.6% in April, 393.9% in July and 27.9% in October. In July, optimized values increase a lot; the slope of the linear regression line increases from 0.162 to 0.65, but in April and October changes in NH_x wet deposition are not as significant as in July. Comparisons between GEOS-Chem and NTN observations are also shown in Zhang et al. [2012]. They

compare the NH₃ wet deposition from GEOS-Chem at the $0.5^{\circ} \times 0.67^{\circ}$ resolution with NTN observations from 2006. The emission inventories of NH₃ they use are different as anthropogenic sources of NH₃ are from NEI-2005 for U.S. with seasonal variability corrected by in situ observations. No significant annual biases and little seasonal bias are found in the comparison. Differences between this study and the present work are the model resolution, the number of months per season included in the comparisons (one vs three) and the emission inventories in the model. We will investigate using additional months and higher resolution inverse models as these become available.

6.3. IMPROVE

For an additional evaluation, we also compare the assimilated results with aerosol ob-359 servations from IMPROVE in 2008. Figure 10 shows that model optimization slightly decreases the sulfate concentrations and increases the nitrate concentrations, which fa-361 cilitates increases in NH₃ concentrations to match TES observations. Still, the changes 362 are small, and the sulfate concentration from the model has a reasonable correlation with 363 the IMPROVE observation before and after optimization in each month. Note that the outlier point in October that has a large observed value but a nearly zero model value is 365 located in Hawaii. The model does not represent this high value owing to the proximity 366 of the observation to the local volcano source. For nitrate, optimization does not help the 367 comparison with the observations, which are initially too high. As modeled NH₃ increases 368 to improve agreement with TES, leading to more nitrate formation, the model nitrate bias becomes even higher compared to IMPROVE. One hypothesis is that HNO₃ formation 370 from N_2O_5 hydrolysis is too high in the model [Zhang et al., 2012]. In contrast Henze et al. [2009] uses sulfate and nitrate to constrain the NH₃ emissions, which implies NH₃ 372

sources are too high. Thus, to achieve closure relative to all data sets, it is evident that assessment of model error beyond NH₃ sources, in terms of scavenging efficiencies and HNO₃ production, is required.

7. Conclusions

Here we have considered the potential for space-based observations of NH_3 to constrain 376 monthly average emissions factors. Initial tests using pseudo-observations show that un-377 der ideal conditions (i.e., a perfect model) using two-weeks worth of TES data, 70% of the variance of the emissions can be constrained in terms of total magnitude. We then proceed to assimilate TES observations for multiple years. Here, we present a range of 380 constrained prediction results and evaluate them with independent data sets. Generally, model optimization increases NH_3 concentrations and NH_x wet deposition; nitrate and 382 sulfate concentrations are not largely impacted. Overall, the model does a better job of 383 capturing the range and variability of NH_3 at AMoN sites in April and October, while 384 in July, the model estimates are consistently biased high. Compared to the wet depo-385 sition observations of NTN, optimization decreases the normalized mean bias (NMB) in April, enhances the NMB in July and October, but overall leads to increased correlation 387 of modeled and observed values. Modeled SO_4^{2-} aerosol concentrations slightly decrease and NO_3^- aerosols concentrations increase, which increases the bias compare to the IM-389 PROVE observation. The large NO₃ aerosols concentrations may due to excessive HNO₃ formation in the model. 391 Overall, we conclude that inverse modeling with satellite information indeed helps con-

Overall, we conclude that inverse modeling with satellite information indeed helps constrain the ammonia emissions, particularly in strong source regions; additional observations or higher resolution inverse models may be necessary to constrain low values. The

findings indicate that the initial NH₃ emissions inventory appears to be broadly under-395 estimated in several areas throughout the U.S., particularly in the west. This is at odds with previous inverse constraints based on nitrate aerosol alone [Henze et al., 2009]. How-397 ever, these results are consistent with more recent works regarding levels in the U.S. and globally [Clarisse et al., 2009; Zhang et al., 2012]. The absolute extent of the emissions underestimation is still in question, as the precise accuracy of the satellite observations is 400 difficult to specify, model resolution is not matched to the satellite resolution, and model processes could have error contributing to uncertainty in the inversion. A greater fraction 402 of peak values are included in the assimilation owing to satellite detection limits, leading to a sampling bias, which may cause the model to overestimate the emissions after op-404 timization. Future work will be applying the model with a higher horizontal resolution (e.g. $0.5^{\circ} \times 0.67^{\circ}$). Also, consideration of bi-directional flux of NH₃ may explain some of these results.

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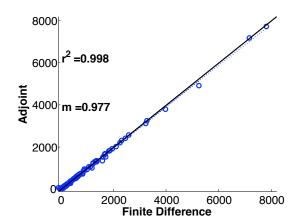


Figure 1. Validation of adjoint model sensitivities via comparison to finite difference (FD) results for week-long simulations. Solid lines are 1:1, dashed are regressions with given r^2 and slope m.



Figure 2. Monitoring sites locations for the Ammonia Monitoring Network (AMoN).

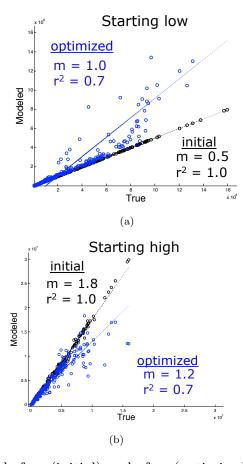


Figure 3. Emissions before (initial) and after (optimized) inversions using TES pseudo observations. To test the inverse model, NH₃ emissions were initialized to values different than the true emissions. In panel (a), the initial emissions are half the true values; in (b), the initial emissions are 1.8 times the true values.

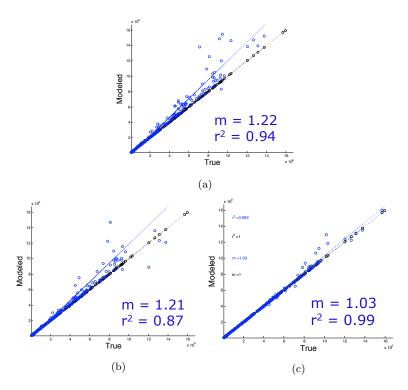


Figure 4. Tests for the possible impacts of inversion error, retrieval bias and measurement error: (a) retrieval algorithm with a polluted profile as an initial guess; (b) modified retrieval algorithm with a moderate profile as the initial guess; (c) model profiles from the true model were ascribed error of the same size as the measurement error.

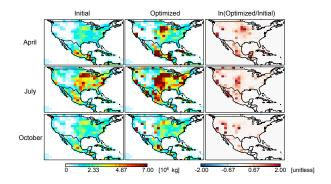


Figure 5. NH₃ emissions from GEOS-Chem before and after the assimilation.

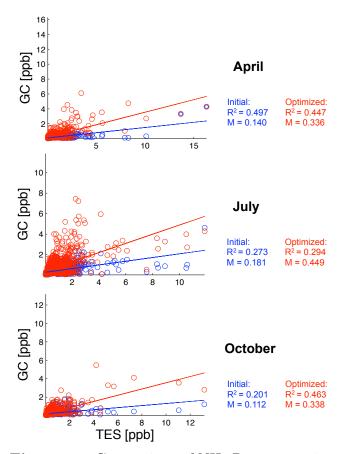


Figure 6. Comparison of NH₃ Representative volume Mixing Ratio (RVMR) from TES and GEOS-Chem before and after the assimilation.

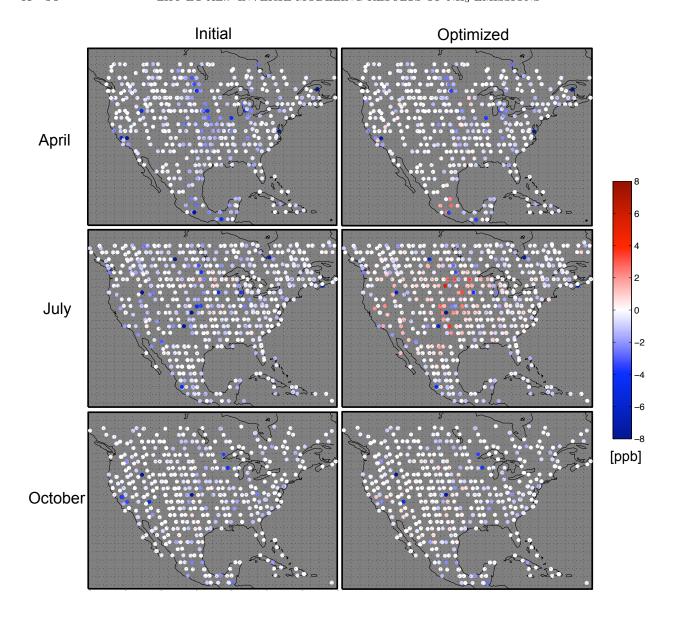


Figure 7. Difference of NH₃ Representative volume Mixing Ratio (RVMR) between TES and GEOS-Chem before and after the assimilation. The left column shows GEOS-Chem initial RVMR - TES RVMR; the right column shows GEOS-Chem optimized RVMR - TES RVMR.

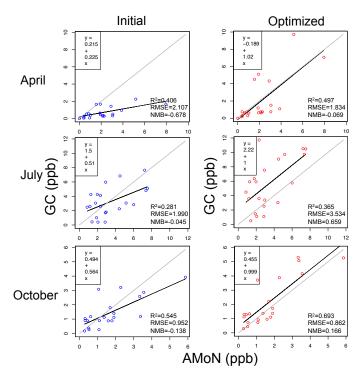


Figure 8. Comparison of GEOS-Chem NH_3 concentrations with observations from AMoN sites before and after the assimilation. The square of the correlation coefficient (R^2) , root mean square error (RMSE), and normalized mean bias (NMB) are shown. Black solid lines are regressions. Grey dashed lines are 1:1.

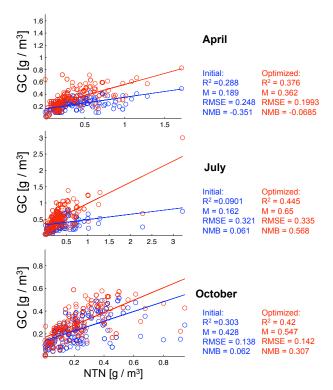


Figure 9. Comparison of GEOS-Chem NH_x wet deposition with observations from NTN(NADP) sites before and after the assimilation.

Table 1. The effects of a priori error emissions (\mathbf{S}_a) on the optimized emissions of different species. Total emissions changes in the U.S. for NH₃, NO_x, and SO₂ when using different values for the diagonal of \mathbf{S}_a in the optimization. E^0 is the initial emissions.

Month	Uncertainties, $\mathbf{S}_a/MAX(E^0)$	Total emissions changes
	$SO_2 NO_x NH_3$	$\Delta SO_2 \Delta NO_x \Delta NH_3$
April	20% 50% 100%	-11.9% -14.69% 112.99%
	50% 50% 50%	-11.58% -15.39% 99.95%
July	20% 50% 100%	-8.35% -4.24% 54.80%
	50% 50% 50%	-10.23% -4.58% 53.26%
October	20% 50% 100%	-3.56% -1.99% 36.07%
	50% 50% 50%	-3.64% -2.41% 35.16%

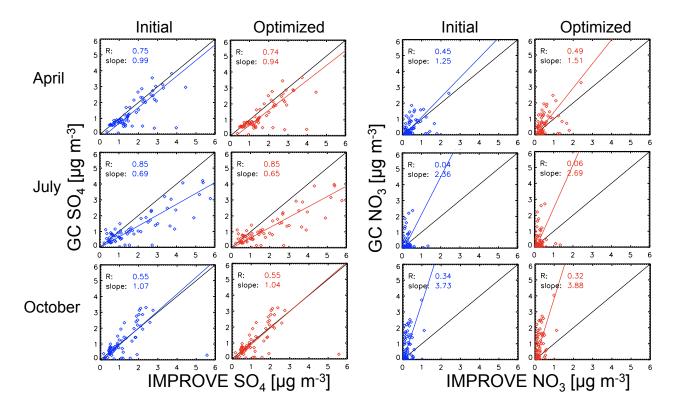
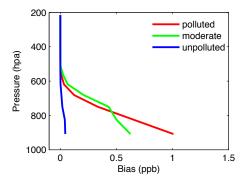
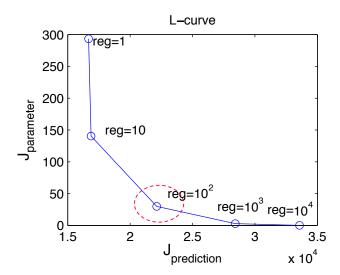


Figure 10. Comparison of GEOS-Chem SO_4 and NO_3 concentrations with observations from IMPROVE sites before and after the assimilation.



Supplementary Figure 1. The average discrepancy between TES retrievals and true profiles [Shephard et al., 2011]. The mean biases are calculated according to the type of the a priori profile used in the retrieval.



Supplementary Figure 2. The L-curve plot used for selecting the regularization parameter (γ) in July. $J_{parameter} = \frac{1}{2} \sum_{\mathbf{c} \in \Omega} (H\mathbf{c} - (\mathbf{c}_{obs} - \mathbf{b}))^T \mathbf{S}_{obs}^{-1} (H\mathbf{c} - (\mathbf{c}_{obs} - \mathbf{b}))$. $J_{prediction} = \frac{1}{2} (\boldsymbol{\sigma} - \boldsymbol{\sigma}_a)^T \mathbf{S}_a^{-1} (\boldsymbol{\sigma} - \boldsymbol{\sigma}_a)$. We select γ to be 100 in this case.